

انواع بال اسپیلاین (لینیربوشینگ شیاردار خطی) ساخت تایوان TBI از سایز mm 6 تا 50 mm





1. About Ball Spline

1-1 Structure and Benefits of *TBI MOTION* Ball Spline

1-1-1 Basic Structure of TBI MOTION Ball Spline

The design of TBI Ball spline is to utilize the friction force through the contact of steel balls within in the Spline Nut and the grooves on the Spline Shaft. With TBI MOTION's unique 40° angular contact design which enables the Ball spline delivers high sensitivity and extreme high load carrying capacity. The concept is optimal for the application involve with high speed, vibrates, impacts of loading and precise positioning requirements. Also when the Ball spline is used to function as linear bushing, the Ball spline provides ten times loading capacity than the linear bushing in the like dimensioned but with a compact profile. Namely, Durability and reliablility is the reason for choosing TBI Ball spline in your application.

1-1-2 TBI MOTION Nut Design and Shaft Specifications

TBI MOTION Spline Nut is available in five different designs: SLF (Flange design), SLT (Non-flange design), SOF (Cylindrical flange design), SOT (Round design), Point of contacts on the Spline shaft is provided in two grooves (180°) (SLF/SLT 6~20), (SOT/SOF 8~25) and four grooves (70°) base on the diameter of the Spline shaft. Also TBI provides Hollow Spline shaft for alternative.

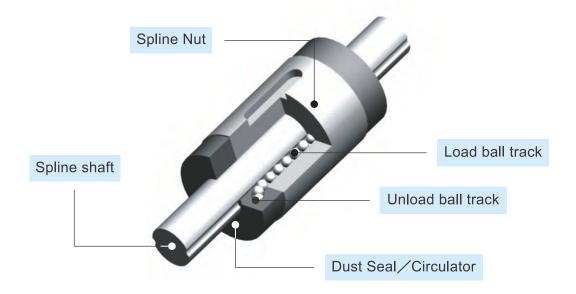


Fig 1.1.1





1-1-3 Features of TBI MOTION Ball Spline

High Load-Carrying Capacity

Every groove on the TBI Spline shaft is precision ground to form a perfect 40° angular contact point. The concept of 40° contact design is to increases the load carrying capacity and rigidity so that it is able to handle a greater moment load.

Zero Angular Clearance / Backlash

Grooves on the TBI Spline shaft is precision ground to form a perfect Gothic arch. The design eliminates clearance that could generate deflections and therefore best suited for the applications that requiring maximum precision.

High Sensitivity

The unique TBI 40° angular contact is design to drive with the minimum of friction force while the design performs not only the highest sensitivity but also the rigidity.

High Rigidity

A wide contact angle and an appropriate level off preload are combined to provide high rigidity and stiffness.

Mount-Simple on Design

TBI Ball spline is low maintenance designed, therefore, even if disassembly is required. When the Spline Nut is necessary to remove for the spline shaft due to the ball retaining design the steel balls will not fall apart like the traditional Nut design.

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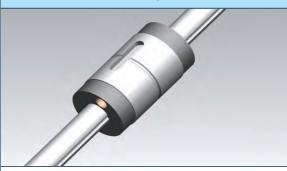
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1-1-4 TBI MOTION Ball Spline Type and Feature

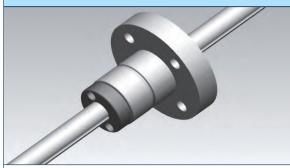
Spline Nut

SLT, SOT Non-flanged Spline Nut



SLT, SOT Spline nut is with a straight cylindrical shape without flange. The standard mode of mounting a cylindrical nut is by using a key. The cylindrical nut will have a keyway and separate key. A matching keyway must be bored into the housing or block that will be mounted on the cylinder nut. The type SLT, SOT is the most compact profile Spline nut in TBI Ball Spline product line.

SLF, Flanged Spline Nut



Flange nut is simpler to install because it only requires a rough bore and mounting holes drilled and tapped to secure the flange to the housing.

SOF, Square Flanged Spline Nut



The nut with square flange is easy to be installed to the housing through mounting holes and will be applied to 3C industry and semiconductor industry.

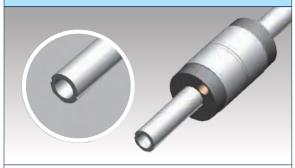
Spline Shaft

Standard Precision Spline Shaft (S-Type)



The Standard precision Spline shaft is precisely ground to reach high accuracy and smoothness.

Hollow Spline Shaft (H-Type)



Hollow Spline shaft is optional for the customer to choose for its application. Hollow Spline shaft is designed to reduce weight, accommodate pipes and ventilation.

Custom Machining Spline Shaft



TBI has the capability to manufacture custom made Spline shaft by machining it to meet the requirements of special Spline Shaft shape. For example, a shaft with a bigger diameter on both ends or on the center of Spline shaft can be manufactured upon request.





1-2 The Procedure of Select Ball Spline

Table 1.2.1

Table 1.2.1		
Steps	Description	
1.Set the Operational conditions	 Stroke Length: Ls Velocity: V The Applied Load: W Size Installation Operation environment Service life expectancy Accuracy Frequency of use (load cycle) Rigidity 	
2.Select a Type	Refer to Type, Shaft Spec to determine the your Ball spline.	
3.Calculating the strength of Spline shaft	 Spline Shaft Diameter Spline-Shaft Length End Fixity The permissible load of Ball spline The displacement under torque and delecting 	
4.Service expectancy	Calculating TBI Ball spline service life expectancy by using expectancy formula. NO NO Required service life.	
5.Determined the preload	Determined the permissible axial clearance / backlash	
6.Determine the Accuracy Grade	Accuracy Grades	
7.Operational condition	 Lubrication Lubrication methods Surface treatment Dust prevention methods 	
	Selected	

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2.Technical Information

2-1 The Strength of Spline Shaft

The Spline shaft is designed to absorb radial load and torque during operation. Therefore, the strength of Spline shaft must be taken into consideration when the Ball spline operates under extreme loading ortorque.

2-1-1 The Bending Load Applied on the Operating Ball Spline

The maximum of bending moment (M) can be attributed to multi factors such as the end fixity methods, length of Spline shaft, load capacity, etc. Equation (1) is equipped to help the user to obtain the ideal length of the Spline shaft in order to be the reference of obtaining the ideal strength of Ball spline.

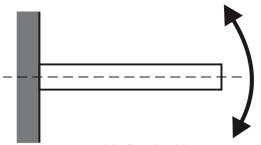
$$M = \sigma \cdot Z$$
 and $Z = \frac{M}{\sigma}$ (1)

M: Bending moment (N-mm)

 σ : Shaft permissible bending stress (98 N/mm²)

Z: Shaft section modulus (mm³)

See Table 2.1.3, 2.1.4



M : Bending Moment

Fig 2.1.1

2-1-2 The Torque Applied on the Operating Ball Spline

The maximum torque applied on the Spline shaft can be calculated through maximum twisting moment (T). Equation (2) is equipped to help the user to obtain the ideal length of the Spline shaft in order to be the reference of obtaining the ideal strength of Ball spline.

$$T = \tau_a \cdot Z_P \text{ and } Z_P = \frac{T}{\tau_a} \dots (2)$$

T: Maximum twisting moment (N·mm)

 τ a : Shaft permissible twisting Stress (49 N/mm²)

Zp: Shaft polar section modulus (mm³)

※ See Table 2.1.3, 2.1.4

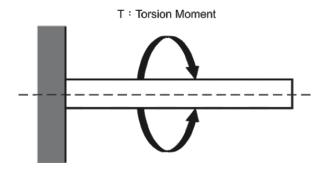


Fig 2.1.2





2-1-3 Both Bending Moment and Twisting Moment Applied Simultaneously on the Spline Shaft

To calculate the figure for both bending (M) and twisting moments (T) applied on the Spline shaft via equation (3) and (4) in order to get the equivalent bending moment (Me) and equivalent twisting moment (Te). Adopt the greater value from equation (3) and (4) to determine the ideal Spline-shaft length.

Equivalent Bending Moment

Me =
$$\frac{M + \sqrt{M^2 + T^2}}{2} = \frac{M}{2} \left\{ 1 + \sqrt{1 + (\frac{T}{M})^2} \right\}$$
(3)

$$Me = \sigma \cdot Z$$

Equivalent Twisting Moment

Te =
$$\sqrt{M^2 + T^2}$$
 = $M \cdot \sqrt{1 + (\frac{T}{M})^2}$ (4)

Te =
$$Ta \cdot ZP$$

2-1-4 Rigidity of the Spline Shaft

The rigidity of the Spline Shaft is expressed in torsion angle caused by twisting moment. The twisting angle should be limited to no further than 0.25° per 1000 mm.

$$\theta = 57.3 \cdot \frac{\mathsf{T} \cdot \mathsf{L}}{\mathsf{G} \cdot \mathsf{I}_{\mathsf{P}}} \dots (5)$$

Shaft Rigidity = Torsion Angle / Unit Length = $\frac{\theta \cdot \ell}{L} < \frac{1^\circ}{4}$

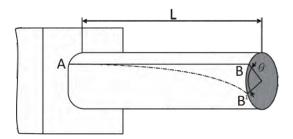


Fig 2.1.3

 θ : Torsion Angle (°)

L: Shaft Length (mm)

G: Shear Elastic Modulus (7.9 · 10⁴ N / mm²)

 ℓ : Unit Length (1000mm)

Ip: Polar Moment of Inertia Ip (mm⁴)

See Table 2.1.3, 2.1.4

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2-1-5 Deflection and Deflection Angle of the Spline Shaft

These should be calculated using equations satisfying the relevant operating conditions. Tables 2.1.1 & 2.1.2 present the operating conditions and the corresponding equations. Tables 2.1.3 & 2.1.4 presents the cross-section factors (Z) and cross-section secondary moments (I). Through the use of the Z, I values given in these tables, the strength and degree of displacement (deflection) of Ball spline model can be obtained.

Table 2.1.1 Deflection and Deflection-Angle Equation

End Fixity	Specification Conditions	Deflection Equation	Deflection-Angle Equation
Both Ends Free	VX P P P P P P P P P P P P P P P P P P P	$\delta \max = \frac{P\ell^3}{48EI}$	$\mathbf{i}_1 = 0$ $\mathbf{i}_2 = \frac{P\ell^2}{16EI}$
Both Ends Fixed	vem Q P	$\delta_{\text{max}} = \frac{P\ell^3}{192EI}$	i = 0 $i = 0$
Both Ends Free	Uniform Load P	$\delta_{\text{max}} = \frac{5P\ell^4}{384EI}$	$\dot{\boldsymbol{i}}_2 = \frac{P\ell^3}{24EI}$
Both Ends Fixed	Uniform Load P	$\delta_{\text{max}} = \frac{P\ell^4}{384EI}$	<i>i</i> 2 = 0



Table 2.1.2 Deflection and Deflection-Angle Equation

End Fixity	Specification Conditions	Deflection Equation	Deflection-Angle Equation
One Ends Fixed	vew o	$\delta \max = \frac{P\ell^3}{3EI}$	$\dot{\boldsymbol{i}} = \frac{P\ell^2}{2EI}$ $\dot{\boldsymbol{i}} = 0$
One Ends Fixed	Uniform Load P	$\delta_{\text{max}} = \frac{P\ell^4}{8EI}$	$i = \frac{P\ell^3}{6EI}$ $i = 0$
Both Ends Free	Couple VEW O	$\delta \max = \frac{\sqrt{3} \operatorname{Mo}\ell^2}{216 \operatorname{EI}}$	$\dot{t}_1 = \frac{M \circ \ell}{12EI}$ $\dot{t}_2 = \frac{M \circ \ell}{24EI}$
Both Ends Fixed	Couple XEE O	$\delta_{\text{max}} = \frac{\text{M o}\ell^2}{216\text{EI}}$	$i = \frac{M \circ \ell}{16EI}$ $i = 0$

 δ max : Maximum Deflection (mm)

 \dot{t} 1 : Deflection Angle at a Loading Point (deg)

 $\dot{\iota}_2$: Deflection Angle at a Supporting Point (deg)

Mo: Moment (N-mm)

P: Concentrated Load (N)

 $p: Uniform\ Load\ (N \diagup mm)$

 ℓ : Span (mm)

I: Geometrical Moment of Inertia (mm⁴)

E: Longitudinal Elastic Modulus

 $(2.06 \cdot 10^5 \text{ N/mm}^2)$

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2-1-6 Critical Speed of Spline Shaft

When an operating Ball spline reaches critical speed, the mechanical resonance occurs and no further operation can be performed under mechanical resonance. Namely, to keep Ball Spline under ideal operational, the speed limit must be kept under monitor. Therefore, to set an ideal operational speed for safety factor must be settled as 80% of critical speed as shown on equation (6)

Critical Speed

$$N_{c} = \frac{60 \lambda^{2}}{2 \pi \cdot \ell_{b}^{2}} \cdot \sqrt{\frac{E \cdot 10^{3} I}{\gamma \cdot A}} \cdot 0.8 \dots (6)$$

Nc: Critical Shaft Speed (min⁻¹)

 ℓ b : Center Distance (mm)

E: Young's Modulus $(2.06 \cdot 10^5 \text{ N/mm}^2)$

I: Moment of Inertia of the Shaft (mm⁴)

$$I = \frac{\pi}{64} d_1^4$$
 d_1 : Diameter (mm)

 γ : Density (Specific Gravity) (7.85·10⁻⁶ kg/mm³)

$$A = \frac{\pi}{4} d_1^2$$
 d₁: Diameter (mm)

A: Spline-Shaft Cross-Sectional Area (mm²)

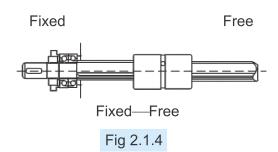
 λ : Installation-Method-Dependent Factor

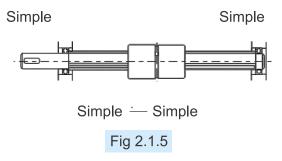
(Fig 2.1.4) Fixed-Free $\lambda = 1.875$

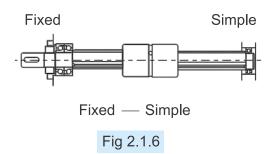
(Fig 2.1.5) Supported-Supported $\lambda = 3.142$

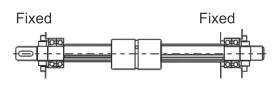
(Fig 2.1.6) Fixed-Supported $\lambda = 3.927$

(Fig 2.1.7) Fixed-Fixed $\lambda = 4.73$









Fixed — Fixed

Fig 2.1.7





2-1-7 Spline-Shaft Cross-Section

Table 2.1.3

Nominal	Diameter	I (mm ⁴)	Ip (mm ⁴)	Z (mm³)	Z _p (mm ³)
01,000	Solid	63.49	119.23	18.58	39.74
SL 006	Hollow	62.70	117.33	18.32	39.22
01,000	Solid	200.93	387.53	46.65	96.88
SL 008	Hollow	196.96	379.57	45.65	94.89
01.040	Solid	490.25	933.29	86.61	186.66
SL 010	Hollow	477.68	908.16	86.10	181.63
01.040	Solid	1400.81	2691.54	198.57	414.08
SL 013	Hollow	1282.96	2455.82	180.44	377.82
01.040	Solid	3215.60	6242.70	378.39	780.34
SL 016	Hollow	3014.53	5840.57	353.25	730.07
01, 000	Solid	7851.80	15336.59	748.48	1533.66
SL 020	Hollow	7360.93	14354.84	699.39	1435.48
01.005	Solid	18466.30	36932.60	1477.30	2954.61
SL 025	Hollow	15981.25	31962.50	1278.50	2557.00
01,000	Solid	33122.31	77392.48	2579.75	4416.31
SL 030	Hollow	29905.32	70958.50	2365.28	3987.38
CL 022	Solid	50322.85	100645.70	3145.18	6290.36
SL 032	Hollow	36586.19	73172.38	2286.64	4573.27
CL 040	Solid	120667.43	241334.90	6033.37	12066.74
SL 040	Hollow	112813.45	225626.90	5640.67	11281.35
CL OFO	Solid	297123.73	594247.50	11884.95	23769.90
SL 050	Hollow	274691.98	549384.00	10987.68	21975.36

I : Geometrical moment of inertia (mm⁴) Ip : Po

Ip: Polar moment of inertia (mm⁴)

Z: Section modulus (mm³)

Z_p: Polar section modulus (mm³)

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Table 2.1.4

Nominal Diameter		I (mm ⁴)	Ip (mm ⁴)	Z (mm ³)	Z _p (mm ³)
CO 000	Solid	200.95	389.81	47.22	97.45
SO 008	Hollow	196.97	381.86	46.22	95.46
00.040	Solid	490.68	956.77	93.22	191.35
SO 010	Hollow	478.11	931.64	90.71	186.33
00.040	Solid	1017.67	1998.75	163.51	333.13
SO 012	Hollow	954.05	1871.52	152.91	311.92
SO 015	Solid	1678.22	3241.10	212.50	476.63
SO 020	Solid	5382.92	10422.07	553.75	1145.28
SO 025	Solid	12796.48	24659.94	1048.86	2182.30

Z: Section modulus (mm 3) $Z_p:$ Polar section modulus (mm 3)





2-2 Service Life Expectancy

2-2-1 Nominal Life

TBI define the nominal life of Ball Spline as 90% of the average running distance before flaking within in the Ball Spline on the same manufacture cycle. Please note that therefore the nominal life expectancy is only for reference use.

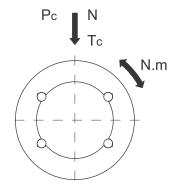


Fig 2.2.1

2-2-2 Calculating Nominal Life

The factors which influence the service life for Ball Splines can be attributed to three main aspects, the torque, radial load and moment. The influence of each aspect can be calculated through equations (7) to (10).

Under a Torque

$$L = \left(\frac{f_{T} \cdot f_{C}}{f_{W}} \cdot \frac{C_{T}}{T_{C}}\right)^{3} 50 \dots (7)$$

Under a Radial Load

$$L = \left(\frac{f_{T} \cdot f_{C}}{f_{W}} \cdot \frac{C}{P_{C}}\right)^{3} \cdot 50 \dots (8)$$

L: Nominal Life (km)

CT: Basic Dynamic-Torque (N-m)

Tc: Calculated Torque Applied (N-m)

C: Basic Dynamic-Load Rating (N)

Pc: Radial Load (N)

f T: Temperature (See Fig 2.2.2)

 f_c : Contact (See Table 2.2.1)

f w : Load Factor (See Table 2.2.2)

Under both a torque and radial load applied simultaneously

In this case, calculate the equivalent radial load to determine service life by equation (9).

$$PE = Pc + \frac{4 \cdot Tc \cdot 10^{3}}{i \cdot BCD \cdot \cos \alpha} \dots (9)$$

PE: Equivalent radial Load (N)

 $\cos \alpha$: Contact Angle

 $\dot{\iota}$: Number of Loaded Rows of Balls

BCD: Ball Center to Center Shaft Diameter (mm)

(See Table 3.1.1)

Under a moment on one spline nut or two closely linked to one another

Obtain the equivalent radial load using the equation, and determine the service life by equation (10).

$$Pu = K \cdot M(10)$$

Pu: Equivalent Radial Load (N)(Moment Applied)

K: Equivalent Factor (See Table 2.2.3)

M: Applied Moment (N-mm)

Hower, M should be within the range of the stacic permissible moment.

Under both a moment and radial load applied simultaneously

Calculate the service life from the sum of the radial load and the equivalent radial load.

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Calculating Nominal Life

Once the nominal life (L) is obtained, if the stroke length and the number of reciprocal operations are consistent, the service life in hours can be obtained by using the following equation.

$$Lh = \frac{L \cdot 10^{3}}{2 \cdot \ell s \cdot n_{1} \cdot 60}(11)$$

Lh: Service Life in Hours (h)

 ℓ s: Stroke Length (m)

n1: Number of Reciprocal Operations per Minute (min⁻¹)

Temperature Factor (f_{T})

When the Ball Spline operates in an environment which the temperature reaches 100°C or higher, considering that the heat may adversely affect the operation of the Ball Spline. To avoid malfunction under extreme temperature, Fig 2.2.2 should be taken into account. In addition that the material of Ball Spline should be heat resistant and custom made when use under extreme environment.

*Please inform TBI sales for upgrading the material for the operation environment exceeds 80°C for the reason that the materials of seal and retainers should be upgraded to sustain the high-temperature.

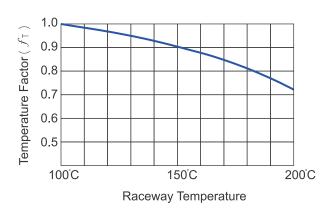


Fig 2.2.2 Temperature Factor (f_{T})

Contact Factor (fc)

When one or multiple Spline nuts mounts on the Spline shaft closeley, their linear motion is affected by moments and mounting accuracy, resulting in nonuniform load distribution. When closely linked spline nuts are used, multiply the basic load rating (C or Co) by one of the contact factors specifiedbelow.

If a non-uniform load distribution is expected, as in large equipment, take the contact factor explained in Table 4 into account.

Table 2.2.1 Contact Factor (f_c)

No. of Spline nuts Linked	fc
2	0.81
3	0.72
4	0.66
5	0.61
In Normal Use	1.0

Load Factor (f w)

The operation of reciprocal machines is likely to cause vibration and impact. It is difficult to determine the rating of vibration, impact in the event of vibration, and repeated impact during high speed operation, and triggering and ceasing of operation. Therefore, when loads exerted on a linear-motion or operation velocity and vibration is extreme. Take the basic load rating (C or Co) and multiply the figure shown in table 2.2.2

Table 2.2.2 Load Factor (f_w)

Vibration Impact	Velocity (V)	£w
Minor	Minor velocity V≦0.25 m/s	1-1.2
Little	Low velocity 0.25 < V ≤ 1.0 m/s	1.2-1.5
Medium	Medium Velocity 1.0 < V ≦ 2.0 m/s	1.5-2.0
Heavy	High velocity V > 2.0 m/s	2.0-3.5



2-2-3 Calculating the Average Applied Load

The Applied load fluctuates during the operation of Ball Spline, For example, the applied load during the activities of an industrial robotic arm is different before holding a workpiece and return without a machine tool, the spline nut of the Ball Spline receives varying loads. Therefore, variables of the applied which influence the to calculate the service life of Ball Spline under on the hose-system operating conditions. The service life of the Ball Spline should therefore be calculated in consideration of such fluctuations in load. The mean load (Pm) is the load under which the service life of the Ball Spline becomes equivalent to that under varying loads exerted on the spline nut while in operation.

The Equation is as below

$$P_{m} = \sqrt[3]{\frac{1}{L} \cdot \sum_{n=1}^{n} (P_{n}^{3} \cdot L_{n})}$$

Pm: Mean Load (N)

Pn: Fluctuating Load (N)

L: Total Running Distance (mm)

Ln: Running Distance Under Load Pn (mm)

For Loads That Change Stepwise

$$P_{m} = \sqrt[3]{\frac{1}{L} (P_{1}^{3} \cdot L_{1} + P_{2}^{3} \cdot L_{2} P_{n}^{3} \cdot L_{n})}$$

Pm: Mean Load (N)

Pn: Fluctuating Load (N)

L: Total Running Distance (mm)

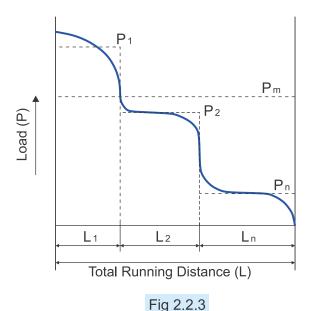
Ln: Running Distance Under Load Pn (mm)

For Loads That Change Monotonically

$$Pm = \frac{1}{3}(P_{min} + 2 \cdot P_{max})$$

Pmin: Minimum Load (N)

Pmax: Maximum Load (N)



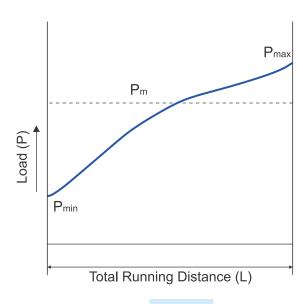


Fig 2.2.4

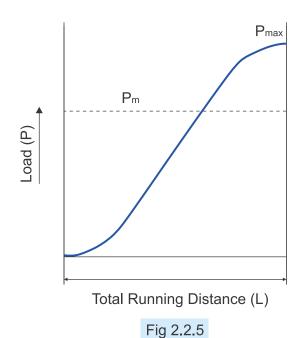
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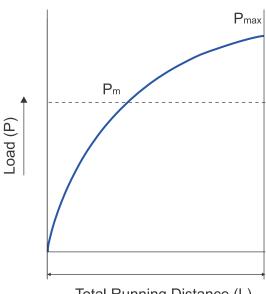


For Loads That Change Sinusoidal





(b) $Pm = 0.75 P_{max}$



Total Running Distance (L)

Fig 2.2.6

2-2-4 Equivalent Factor

Table 2.2.3 Equivalent Factor

	Equivalent	Factor : K
Model No.	One Spline Nut	Two Spline Nuts
SL 06	0.577	0.065
SL 08	0.577	0.059
SL 10	0.418	0.047
SL 13	0.360	0.043
SL 16	0.229	0.033
SL 20	0.201	0.029
SL 25	0.154	0.023
SL 30	0.126	0.021
SL 32	0.114	0.019
SL 40	0.110	0.016
SL 50	0.109	0.013

	Equivalent Factor : K		
Model No.	One Spline Nut	Two Spline Nuts	
SO 08	0.400	0.061	
SO 10	0.308	0.052	
SO 12	0.253	0.046	
SO 15	0.219	0.040	
SO 20	0.186	0.031	
SO 25	0.154	0.026	

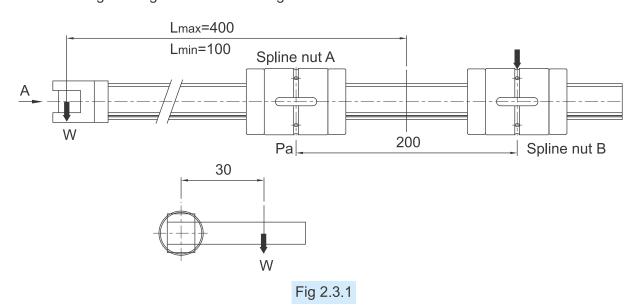




2-3 Calculating the Service Life

Horizontal Application

A 300 mm long Ball Spline supported by two fixed nuts on each end setup for an horizontal application, the load of the Spline falls vertically downward on the fixed side with 30 mm away from the center of ball spline with the gravity force of W = 30 kg. The figure is shown as Fig 2.3.1



A.Calculates the Spline Shaft Strength

The present structure of ball spline is an extended bridge, it is designed to absorb torque, therefore, the maxima bending load occurs on Spline nut A:

Maxima Bending Moment $M = 30 \cdot 9.81 \cdot 400 = 117720 \text{ N-mm}$

Maxima Torsion Moment $T = 30 \cdot 9.81 \cdot 30 = 8829 \text{ N-mm}$

For Ball Spline shafts subjected to the simultaneous application of torsion and bending loads, thus the calculation should include Equivalent Bending Moment, Me and Equivalent Torsion Moment Te:

$$Me = \frac{M + \sqrt{M^2 + T^2}}{2} = 117885 \text{ N-mm}$$
 $Te = \sqrt{M^2 + T^2} = 118051 \text{ N-mm}$

Te > Me

∴ Te =
$$\tau$$
 a · Zp

$$\therefore$$
 Zp = Te/ τ a = 118051/49 = 2409.2 mm³

According to figure of cross section showed on the spline (Table 2.1.3, 2.1.4), the minimum of 25 mm in diameter is required to in order to gain enough of strength for Ball Spline, therefore, SLF25 matches the requirement above thus choose SLF25.

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B.Calculating the Mean Load

When the bridge extension reached Lmax = 400mm, it reaches it' maxima load (Pmax) When it retrieved back to Lmin = 100mm, it absorbed the minimum of load (Pmin) According to mechanics it allows us to find out the maxima and minimum Radial Load of Nut A and nut B:

$$P_{Amax} = 30 \cdot 9.81 \cdot (400+200) / 200 = 882.9 \text{ N}$$

$$P_{Bmax} = 30 \cdot 9.81 \cdot 400 / 200 = 588.6 \text{ N}$$

$$P_{Amin} = 30 \cdot 9.81 \cdot (100+200) / 200 = 441.5 N$$

$$P_{Bmin} = 30 \cdot 9.81 \cdot 100 / 200 = 147.2 \text{ N}$$

When the movement of Ball Spline occurs, the load on the spline is gradual and repeated, according to Fig 2.2.4 the equation of the load on ball spline is shown as:

$$P_{AM} = 1/3 (P_{AMin} + 2P_{AMax}) = 735.8 N$$

$$P_{BM} = 1/3 (P_{Bmin} + 2P_{Bmax}) = 441.5 N$$

The nuts receive both torsion and bending load simultaneously, therefore assuming that the torsion lies equally on the nuts. The equation for torsion is shown as T ':

T' =
$$T/2 = 30 \cdot 9.81 \cdot 30/2 = 4414.5 \text{ N-mm}$$

The equivalent factor Pe (B12, equation (9)):

$$Pe = Pm + \frac{4 \cdot T'}{i \cdot dp \cdot \cos \alpha}$$

$$PAE = 735.8 + \frac{4 \cdot 4414.5}{4 \cdot 27 \cdot \cos 50} = 990.2 \text{ N}$$

$$PBE = 441.5 + \frac{4 \cdot 4414.5}{4 \cdot 27 \cdot \cos 50} = 695.9 \text{ N}$$

C.Service Life Ball Spline

Nut A life LA =
$$\left(\frac{f_T \cdot f_C}{f_W} \cdot \frac{C}{P_{AE}}\right)^3 \cdot 50 = 14518 \text{ km}$$

Nut B life L_B = $\left(\frac{f_T \cdot f_C}{f_W} \cdot \frac{C}{P_{BE}}\right)^3 \cdot 50 = 41829 \text{ km}$

 f_T : Temperature = 1

fc: Friction = 1

fw : Load = 1.5

C: Coa = 9835 N

The service life of Ball Spline is correlated with Nut A and the of service life is estimated as 14518 km.





Vertical Application

A 1200 mm long ball spline with stroke of 1000 mm is mounted on a working platform supported by two fixed nuts on both end. The geometry is shown as Fig 2.3.2

The point of drive force F is X1 = 50 mm, from the center of Ball Spline, the weight platform W1 is 27 kg, the center of the weight is X2 = 300 mm, away from the center of ball spline, the working cycle of platform is a carriage of W2 = 5 kg, with a downward movement for 5 sec hold for 10 sec, and elevation for 5 sec hold for 10 sec to unload the carriage repeatedly. The center of gravity of carriage is X3 = 500 mm, from the center of ball spline, the travelling of velocity is shown as Fig 2.3.2

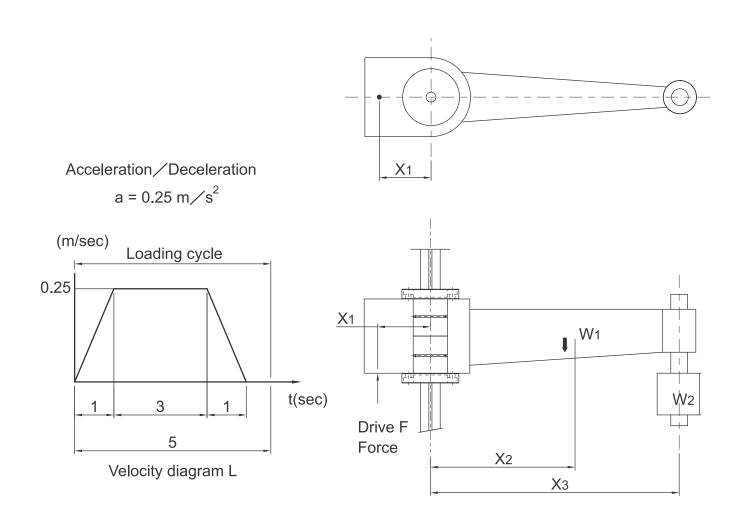


Fig 2.3.2

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A. Analysis on Different Stage of Exertion

Inertial force occurs when a platform is in working modes, drive force is the source of the inertial force.

Inertial force of a m/s² in acceleration ascent and deceleration decent : $F = W \cdot (9.81+a)$ Inertial force of Constant velocity in acceleration and deceleration : $F = W \cdot (9.81)$ Inertial force of a m/s² in acceleration decent and deceleration ascent : $F = W \cdot (9.81-a)$

Below are the equations of the bending force absorb by the nuts during acceleration, constant velocity, deceleration while ball ascent and decent.

(1) Without carriage (Acceleration while decent)

$$M_{da} = W_1 \cdot (9.81-a) \cdot 300 + W_1 \cdot (9.81-a) \cdot 50 = 90342 \text{ N-mm}$$

(2) Without carriage (Constant velocity while decent)

$$Mdc = W1 \cdot (9.81) \cdot 300 + W1 \cdot (9.81) \cdot 50 = 92704.5 \text{ N-mm}$$

(3) Without carriage (Deceleration while decent)

$$Mdd = W1 \cdot (9.81+a) \cdot 300 + W1 \cdot (9.81+a) \cdot 50 = 95067 \text{ N-mm}$$

(4) With carriage (Acceleration while ascent)

$$Maa = W1 \cdot (9.81+a) \cdot 300 + W1 \cdot (9.81+a) \cdot 50 + W2 \cdot (9.81+a) \cdot 500 + W2 \cdot (9.81+a) \cdot 50$$

= 122732 N-mm

(5) With carriage (Constant velocity while ascent)

$$Mac = W1 \cdot (9.81) \cdot 300 + W1 \cdot (9.81) \cdot 50 + W2 \cdot (9.81) \cdot 500 + W2 \cdot (9.81) \cdot 50$$

= 119682 N-mm

(6) With carriage (Deceleration while ascent)

$$Mad = W1 \cdot (9.81-a) \cdot 300 + W1 \cdot (9.81-a) \cdot 50 + W2 \cdot (9.81-a) \cdot 500 + W2 \cdot (9.81-a) \cdot 50$$

= 116632 N-mm





B. The Calculation of Spline Strength

The present structure of ball spline is supported by two fixed nuts on both ends with an bridge of absorbing bending in the middle. it designed to absorb torque. According to mechanics the maxima bending load occurs on the supporting end. The Maxima Bending Moment should occur on at the end of acceleration.

$$\therefore$$
 Z = M/ σ a = 122732/98 = 1252.4 mm³

According to figure of cross section showed on the spline, the minimum of 25 mm in diameter is required to in order to gain enough of strength for Ball Spline, therefore SLF25 matches the requirement above thus choose SLF25.

C. Calculating the Mean Load

The nuts and spline mainly affect by the force of bending, therefore represent (B12, equation (10)) by converting the force of bending into radial load.

$$Pn = K \cdot M$$

According to Table 2.2.3, when joint two SLF25 nuts, The equivalent factor K = 0.023

Pda = 0.023 · 90342 = 2078 N	Paa = 0.023 · 122732 = 2822.8 N
$Pdc = 0.023 \cdot 92704.5 = 2132.2 \text{ N}$	Pac = 0.023 · 119682 = 2752.7 N
$Pdd = 0.023 \cdot 95067 = 2186.5 N$	Pad = 0.023 · 116632 = 2682.5 N

The average load in every time peroid can be calculate as Pm:

	Pm : Average Load	(N)
2 / 4 n	Pn : Load in variable	(N)
$Pm = \sqrt[3]{\frac{1}{I}} \cdot \sum_{n=1}^{\infty} (Pn^3 \cdot Ln)$	L : Total service distances	(mm)
n=1	Ln: Pn Service distances	(mm)
	under loading	

$$P_{m} = \sqrt[3]{\frac{1}{1000}} \left\{ 125 \cdot 2078^{3} + 750 \cdot (2132.2)^{3} + 125 \cdot (2822.8)^{3} + 750 \cdot (2752.7)^{3} + 125 \cdot (2682.5)^{3} \right\}$$

= 2481.6 N

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D. Analysis of Ball Spline Service Life

Service Life L =
$$\left(\frac{f_{\text{T}} \cdot f_{\text{C}}}{f_{\text{W}}} \cdot \frac{\text{C}}{P_{\text{m}}}\right)^{3} \cdot 50 = 922 \text{ km}$$

$$f$$
 T : Temperature = 1
 f C : Friction = 1
 f W : Load = 1.5
 \mathbf{C} : Coa = 9835 N

2-4 Determining the Preload

The preload a significant factor toward the accuracy, load resistance and rigidity of Ball Spline during operation. Therefore, it is very important to determine the most appropriate size of the clearance for your purpose of use. The size of the clearance is standardized for each type, enabling the one best-suited for operating conditions to be selected.

2-4-1 Clearance in the Rotational Direction

With the Ball Spline, the sum of clearances in the circumferential direction is standardized as the clearance in the rotational direction.

Clearance in the Rotational Direction. (BCD)

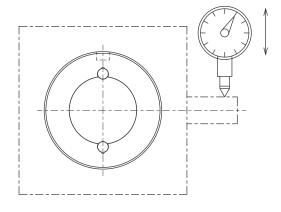


Fig 2.4.1

2-4-2 Preload and Rigidity

The preload is the load applied to balls prior to use for the purposes of eliminating angular backlash (clearance in the rotational direction)

and improving rigidity. The application of a preload can eliminate angular backlash in the Ball Spline in accordance with the level of applied preload, and can improve rigidity. Fig. 2.4.2 shows the amount of displacement in the rotational direction when a rotational torque

is applied. As shown, the effect of preloading continues until the torque becomes Fig 2.4.2 times greater than the preload applied. Compared with a setting without a preload, displacement at the same rotational torque is half that under a preload or less, and the rigidity is twice as great.

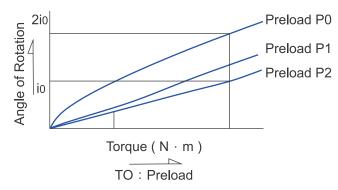


Fig 2.4.2





Unit : μ m

2-4-3 Operating Conditions and Determination of the Preload Level

Table 2.4.1 presents guidelines for determining the appropriate clearance in the rotational direction for the given operating conditions. The rotational clearance of the Ball Spline significantly affects the accuracy and rigidity of the Spline nut. Therefore, it is critical to select the clearance best suited for the intended uses of the Ball Spline. Normally, the Ball Spline in use is preloaded. When it is subjected to repeated swiveling and reciprocal linear motion, a system receives heavy vibration and impact. In such an environment, preloading prolongs the service life and improves accuracy.

Table 2.4.1 Guidelines for Determining an Appropriate Ball Spline Clearance according the Rotational Direction.

		Preload	Operating conditions	Applications
ection	ection	Medium Preload P2	 High rigidity is required. Vibration and impact are severe. The moment load must be borne by a single spline nut. 	 Construction-work-vehicle steering shaft. Spot-welding-machine shaft. Automatic-lathe-tool rest indexing shaft.
	ce in the Rotational Direction		applied.Highly reproducible accuracy is required.	 Industrial robot arm Various automatic. loaders. Automatic-painting-machine guide shaft. Electric-discharge-machine spindle. Press die-set guide shaft. Drilling-machine spindle.
	Clearance	No Preload P0	 Smooth movement should be achieved with only a low magnitude of force. Torque is continually applied in a given direction. 	 Various measuring instruments. Automatic drafting machine. Shape-measuring instrument. Dynamometer. Wire winder. Automatic arc cutter. Honing-machine spindle. Automatic packing machine.

Table 2.4.2 Ball spline Clearance in the Rotational Direction

Nom Dian		· ·	Pı	relo	oad	No Preload P0	Slight Preload P1	Medium Preload P2
6	8	10	12	2	13	-2~+1	-6~-2	-
15	15 16 20		-2~+1	-6~-2	-9~-5			
	25 30		-3~+2	-10~-4	-14~-8			
40 50		-4~+2	-16~-8	-22~-14				

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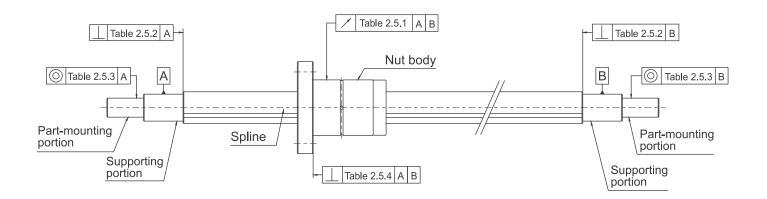




2-5 Accuracy

2-5-1 Accuracy Grade

The accuracy of the Ball Spline is determined by the spline-nut and thus divided into three accuracy grades of Normal(N), High(H), and Precision(P).



2-5-2 Accuracy Specifications

Tables 2.5.2~2.5.5 indicates the tolerance of callout of the Ball Spline.

Table 2.5.1 The tolerance of Spline Nut on the Support Unit

Nominal Diameter (mm)		6, 8				10			12, 13, 15, 16, 20			25, 30			40, 50		
Above	Below	N	Н	Р	N	Н	Р	N	Н	Р	N	Н	Р	N	Н	Р	
-	200	72	46	26	59	36	20	56	34	18	53	32	18	53	32	16	
200	315	133	89	57	83	54	32	71	45	25	58	39	21	58	36	19	
315	400	185	126	82	103	68	41	83	53	31	70	44	25	63	39	21	
400	500	236	163	108	123	82	51	95	62	38	78	50	29	68	43	24	
500	630	-	-	-	151	102	65	112	75	46	88	57	34	74	47	27	
630	800	-	-	-	190	130	85	137	92	58	103	68	42	84	54	32	
800	1000	-	-	-	-	-	-	170	115	75	124	83	52	97	63	38	
1000	1250	-	-	-	-	-	-	-	-	-	151	102	65	114	76	47	



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Unit : μ m



Table 2.5.2 The Maximum Perpendicularity of Spline Shaft End on the Journal Ends Unit: μ m

Nor Dia	minal mete	er (m		ccu	ıracy	Normal (N)	High (H)	Precision (P)
6	3	8	8 10		10 22		9	6
12	13	15	1	6	20	27	11	8
	25 30)	33	13	9		
	40 50		39	16	11			

Table 2.5.3 The Maximum Radial Call Out on the Attach Surface

Nor Dia	minal mete	r (m		uracy	Normal (N)	High (H)	Precision (P)
6 8			8		33	14	8
	10				41	17	10
12	13	15	16	20	46	19	12
	25 30		53		22	13	
40 50		62	25	15			

Table 2.5.4 The Perpendicularity of Flange on the Attach Surface

Nor Dia	Accuracy Nominal Diameter (mm)			CCI	uracy	Normal (N)	High (H)	Precision (P)
	6 8			17	11	8		
1	0	12	2		13	33	13	9
15	16	20	25 30		30	30	16	11
	40 50		46	19	13			

Table 2.5.5 The Accuracy Level on the Effective Length Accuracy

Accuracy	Normal (N)	High (H)	Precision (P)
Permissible	33	13	6

^{*}Measurement according to any 100mm on the Spline shaft.

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Unit: μ m

Unit : μ m

Unit : μ m





2-6 Lubrication

The spline nut is prelubricated prior to shipment for immediate use and the maintenance period is varied according to the operating conditions. TBI suggested that under normal operation condition re-lubricate your TBI Ball Spline after 100 Km (6-12 months) of operation. Apply lubricant within the nut body or on the groove of Spline shaft.

2-7 Material and Surface Treatment

TBI MOTION provides customize material and surface treatment in order to meet extreme operation condition. Please contact TBI MOTION service window for customized surface treatment and material.

2-8 Precautions of Ball Spline

2-8-1 General Maintenance

- (1) Disassemble ball spline without supervise of *TBI MOTION* certified engineer will cause malfunction on the ball spline.
- (2) Gravity causes the spline nut slides when lining the ball spline, handle with care.
- (3) Do not hammer, free fall the ball spline such action will damaging the ball spline and might hinder the performance of ball spline.
- (4) Prevent debris, scraps from intervene the ball spline cause it will decrease the performance to ball spline or lead to malfunction.
- (5) Prevent the ball spline operates under extreme condition. Contact *TBI MOTION* service window when the TBI ball spline is intend to use under extreme condition.
- (6) Coolant might casue malfunction on the ball spline, please contact *TBI MOTION* certified engineer for consulting the use of coolant.
- (7) Clean attached debris and scraps before relubrication.
- (8) Please contact *TBI MOTION* certified engineer for consulting when the ball spline is designed to operates under frequently vibrates, vacuum, extreme high and low temperature condition.
- (9) Please contact *TBI MOTION* certified engineer for consulting when mounting a through hole on the flanged ball spline.





2-8-2 Lubrication

- (1) Remove anti-dust oil before seal the ball spline with grease.
- (2) Prevent mix different kind of grease, it will cause unexpected chemical deform.
- (3) Please contact *TBI MOTION* certified engineer for consulting the use of grease when the ball spline is designed to operates under frequently vibrates, vacuum, extreme high and low temperature condition.
- (4) Please contact *TBI MOTION* certified engineer for consulting the use NON *TBI MOTION* certified grease.
- (5) When using of motor oil to serve the purpose of lubrication, it might cause performance declining due to the un-proper installation. Please contact *TBI MOTION* certified engineer for consulting.

2-8-3 Storage

Prevent extreme temperature and humidity when store ball spline, also use *TBI MOTION* certified seal and storage and it in a horizontal position.

2-9 Mounting

2-9-1 Tolerance on Support Unit

Ball spline nut and its support unit is bore to minimize the clearance. If high accuracy is not required, then a clearance fit can be used.

Table 2.9.1

Condition	Tolerance within Support Unit
General Operation Condition	H7
Operation Under Minimize of Axial Clearance	J6

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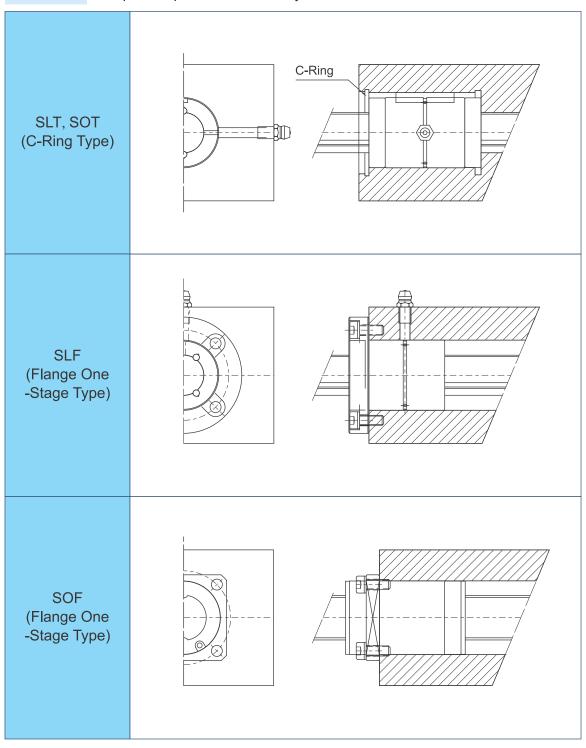
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2-9-2 Installation of Ball Spline

The installation of the ball spline is shown as Fig 2.9.2 Though the strength of mounting is not strictly standard, but it has to be certain that the spline shaft has to be firmly fixed on the support unit.

Table 2.9.2 Sample of Spline-Nut Assembly





Unit: mm

2-9-3 Installation of Spline Nut

When intalling a spline nut into the spline shaft, use a jig like Fig 2.9.1 to insert the spline but with care.

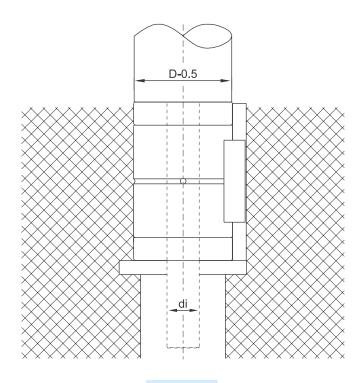


Fig 2.9.1

Table 2.9.3 Specifications of the jig

Model	Nominal Diameter	6	8	10	13	16	20	25	30	40	50
SL	di	5.0	7.0	8.5	11.5	14.5	18.5	23	28	37.5	46.5
Model	Nominal Diameter	-	8	10	12	15	20	25	-	-	-
SO	di	-	7.0	8.5	10.5	11	16	20.5	-	-	-

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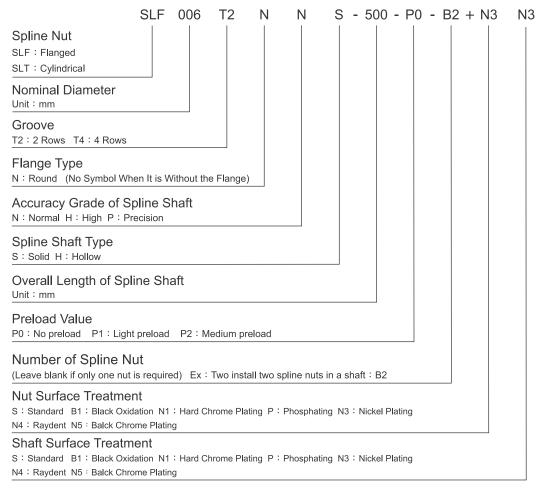
3. TBI MOTION Ball Spline

3-1 Nominal Model Code of Ball Spline SL Series

3-1-1 Nominal Model Code

TBI MOTION ball Splines can be classified into interchangeable and non- interchangeable types. Their dimensions are the same; the only difference between the two types is that for non-interchangeable series, TBI MOTION will finish every process in the production line and hit customers' demands for preload and accuracy. Interchangeable nuts and shafts can be freely exchanged and the standard of the preload is P0. Customers could adjust the preload by changing the steel balls inside of the nut by themselves. It is very convenient for customers to have TBI MOTION ball splines in inventory and make the preload and end machining by themselves. TBI MOTION is proud of internal quality control process which is under strict international regulation.

Non-interchangeable Type Code:



※No symbol required when no plating is need.



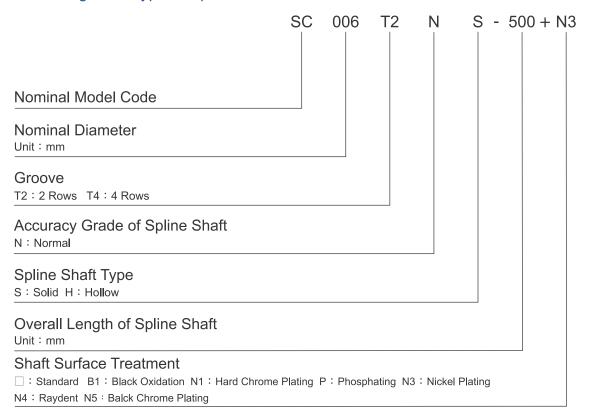


Nominal Model Code for Interchangable SL Type

Interchangeable Type of Spline Nut:



Interchangeable Type of Spline Shaft:



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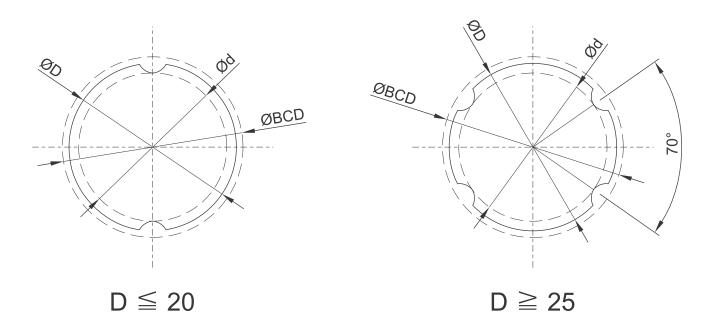
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SLF, SLT Spline Shaft Cross-Sectional Shape

Table 3.1.1, 3.1.2 indicates the cross-section of spline shaft. When the shaft end is round pillar type the minor diameter must not be greater than the diameter of groove ridge.



Solid Spline Shaft

Table 3.1.1 Solid Spline Shaft Cross-Sectional Shape

Nominal Diameter Stats	6	8	10	13	16	20	25	30	40	50
Inner Diameter Ød	5.25	7.27	8.97	11.82	14.72	18.63	23.43	28.53	37.3	47.05
Outer Diameter ØD h7	6	8	10	13	16	20	25	30	40	50
Mass (kg/m)	0.22	0.39	0.6	1.03	1.56	2.44	3.8	5.49	9.69	15.19
Ball Center ØBCD	6.75	8.77	11.35	14.6	17.5	21.8	27	32.1	43.65	54.2
Tolerance μ m	0 - 15	0 - 15	0 - 18	0 - 18	0 - 18	0 - 21	0 - 21	0 - 25	0 - 25	0 -30



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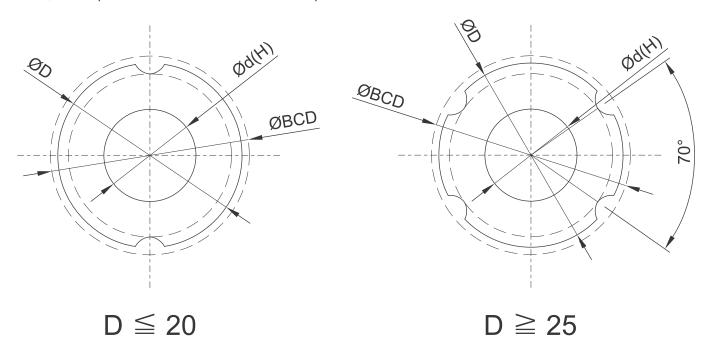
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Unit: mm



Unit: mm

SLF, SLT Spline Shaft Cross-Sectional Shape



Hollow Spline Shaft

Table 3.1.2 Hollow Spline Shaft Cross-Sectional Shape

Nominal Diameter Stats	6	8	10	13	16	20	25	30	40	50
Inner Diameter Ød	2	3	4	7	8	10	15	16	20	26
Outer Diameter ØD h7	6	8	10	13	16	20	25	30	40	50
Mass (kg/m)	0.177	0.33	0.506	0.872	1.25	1.82	2.92	3.93	6.75	11.4
Ball Center ØBCD	6.75	8.77	11.35	14.6	17.5	21.8	27	32.1	43.65	54.2
Tolerance μ m	0 -15	0 -15	0 -18	0 -18	0 -18	0 -21	0 -21	0 -25	0 -25	0 -30

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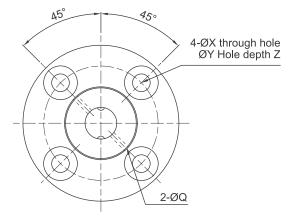


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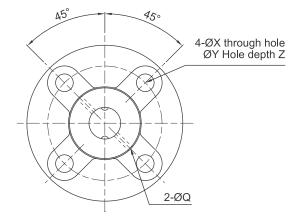
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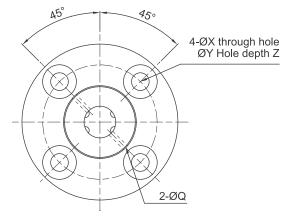
SLF Series Specifications



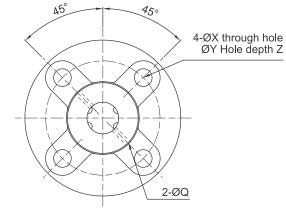
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[Two Starts] Type: 08 \ 16 \ 20



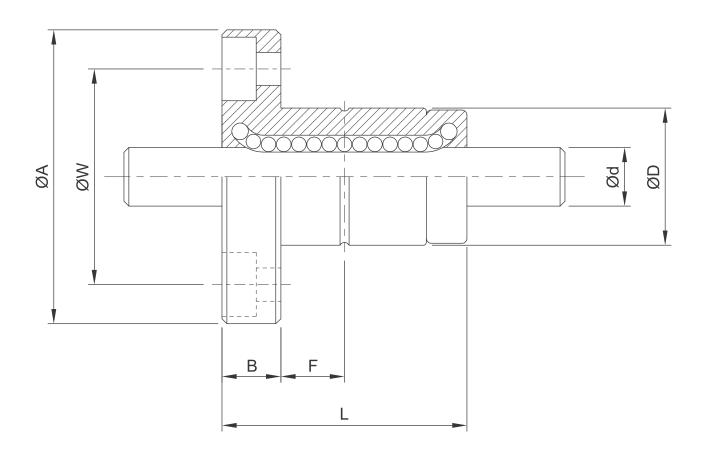
[Four Starts] Type: 40 \ 50



[Four Starts] Type: 25 \ 30

	Diameter		Spline Nut Dimension									
Model No.	d	Row	D	L	А	В	F	Oil	W	Mounting Hole		
	h7		U	_	A	Ь	Г	Q	VV	X·Y·Z		
SLF006	6	2	14	25	30	6	7.5	1	22	3.4 · 6.5 · 3.5		
SLF008	8	2	16	27	32	8	7.5	1.5	24	3.4 · 6.5 · 4.5		
SLF010	10	2	21	33	42	9	10.5	1.5	32	4.5 · 8 · 4		
SLF013	13	2	24	36	44	9	11	1.5	33	4.5 · 8 · 4.5		
SLF016	16	2	31	50	51	10	18	2	40	4.5 · 8 · 6		
SLF020	20	2	35	56	58	10	18	2	45	5.5 · 9.5 · 5.4		
SLF025	25	4	42	71	65	13	26.5	3	52	5.5 · 9.5 · 8		
SLF030	30	4	47	80	75	13	30	3	60	6.6 · 11 · 8		
SLF040	40	4	64	100	100	18	36	4	82	9 · 14 · 12		
SLF050	50	4	80	125	124	20	46.5	4	102	11 · 17.5 · 12		





	Basic Loa	ad Rating	Basic ⁻	Torsion	Static Pe Mor	rmissible nent	Mass		
Model No.	С	C ₀	Ст	Сот	MA1	MA2	Spline Nut	Spline Shaft	
	kgf	kgf	kgf · m	kgf · m	kgf · m	kgf · m	g	kg/m	
SLF006	137	225	0.46	0.76	0.39	3.48	36.7	0.22	
SLF008	137	225	0.60	0.99	0.39	3.82	47	0.39	
SLF010	285	397	1.62	2.25	0.95	8.53	100	0.60	
SLF013	396	540	2.89	3.94	1.50	12.46	117	1.03	
SLF016	545	849	4.77	7.43	3.71	26.09	226	1.56	
SLF020	724	1109	7.90	12.09	5.53	38.00	303	2.44	
SLF025	1003	1593	21.99	43.01	10.35	68.59	458	3.80	
SLF030	1160	1980	30.26	62.93	15.68	93.27	633	5.49	
SLF040	2972	4033	105.37	176.05	36.59	246.34	1430	9.69	
SLF050	4086	5615	179.89	304.35	51.58	428.72	2756	15.19	

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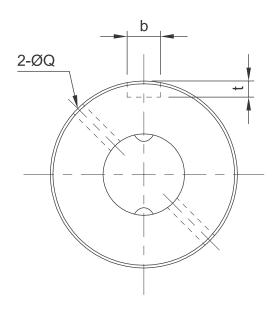
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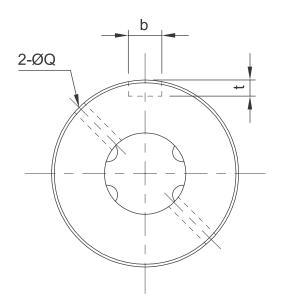




SLT Series Specifications



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< Four row >

Shaft diameter $d \le 20$ Shaft diameter $d \ge 25$

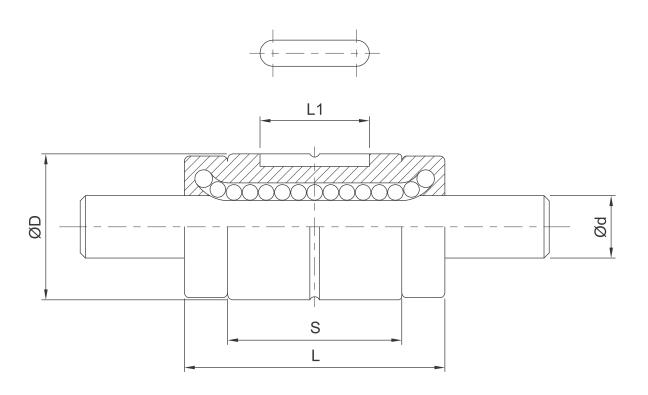
	Diameter			Spline	Keyway Dimensions				
Model No.	d	Row	D		S	L1	Oil	b	t
	h7		D	L	3	LI	Q	H8	+0.05 ~0
SLT006	6	2	14	25	16.7	10.5	1	2.5	1.2
SLT008	8	2	16	27	15.7	10.5	1.5	2.5	1.2
SLT010	10	2	21	33	20	13	1.5	3	1.5
SLT013	13	2	24	36	23	15	1.5	3	1.5
SLT016	16	2	31	50	34	17.5	2	3.5	2
SLT020	20	2	35	56	39.7	29	2	4	2.5
SLT025	25	4	42	71	50.3	36	3	4	2.5
SLT030	30	4	47	80	60	42	3	4	2.5
SLT040	40	4	64	100	70	52	4	6	3.5
SLT050	50	4	80	125	91	58	4	8	4



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📈 فكس : 33985603 (021)





	Basic Load Rating		Basic Torsion		Static Permissible Moment		Mass	
Model No.	С	C ₀	Ст	Сот	MA1	MA2	Spline Nut	Spline Shaft
	kgf	kgf	kgf · m	kgf · m	kgf · m	kgf · m	g	kg/m
SLT006	137	225	0.46	0.76	0.39	3.48	14	0.22
SLT008	137	225	0.60	0.99	0.39	3.82	16	0.39
SLT010	285	397	1.62	2.25	0.95	8.53	37	0.60
SLT013	396	540	2.89	3.94	1.50	12.46	52	1.03
SLT016	545	849	4.77	7.43	3.71	26.09	130	1.56
SLT020	724	1109	7.90	12.09	5.53	38.00	188	2.44
SLT025	1003	1593	21.99	43.01	10.35	68.59	285	3.80
SLT030	1160	1960	30.26	62.93	15.68	93.27	395	5.49
SLT040	2972	4033	105.37	176.05	36.59	264.34	843	9.69
SLT050	4086	5615	179.89	304.35	51.58	428.72	1758	15.19

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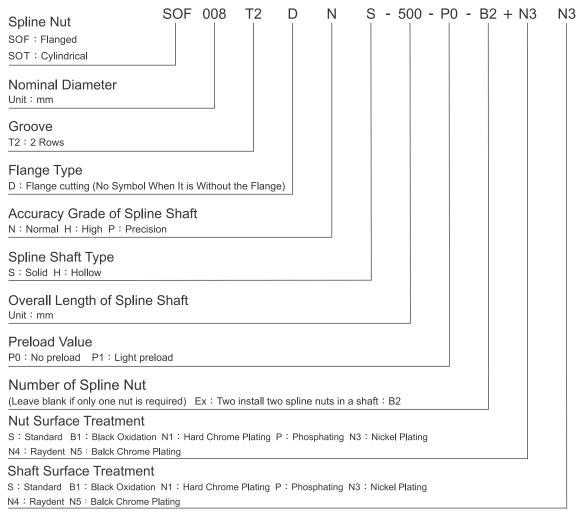


3-2 Nominal Model Code of Ball Spline SO Series

3-2-1 Nominal Model Code

TBI MOTION ball Splines can be classified into interchangeable and non- interchangeable types. Their dimensions are the same; the only difference between the two types is that for non-interchangeable series, TBI MOTION will finish every process in the production line and hit customers' demands for preload and accuracy. Interchangeable nuts and shafts can be freely exchanged and the standard of the preload is P0. Customers could adjust the preload by changing the steel balls inside of the nut by themselves. It is very convenient for customers to have TBI MOTION ball splines in inventory and make the preload and end machining by themselves. TBI MOTION is proud of internal quality control process which is under strict international regulation.

Non-interchangeable Type Code:

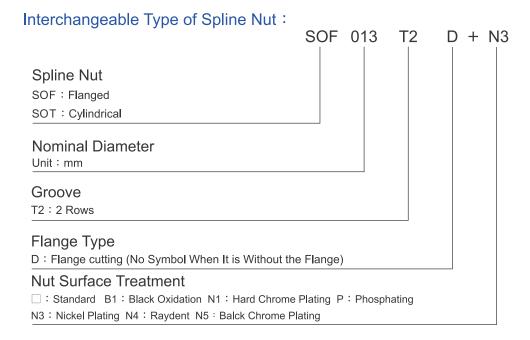


No symbol required when no plating is need. (see B29)

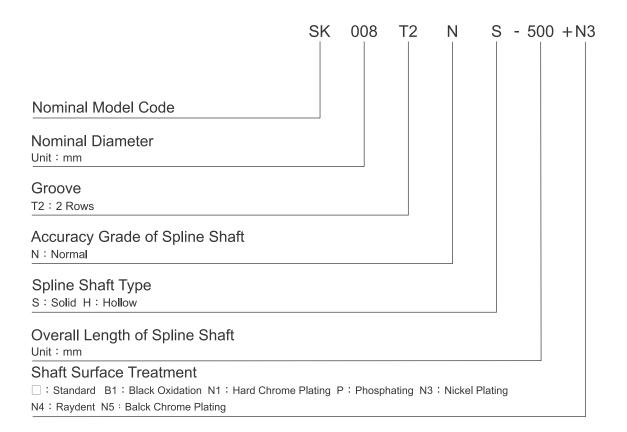




Nominal Model Code for Interchangable SO Type



Interchangeable Type of Spline Shaft:



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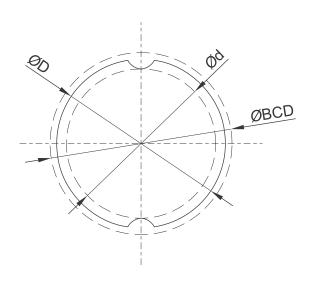


بلبرينگ اسكوئي

(اسکو صنعت تاوریژ)



SOF, SOT Spline Shaft Cross-Sectional Shape



Solid Spline Shaft

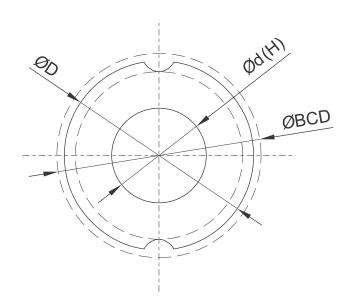
Table 3.2.1 Solid Spline Shaft Cross-Sectional Shape Unit: mm

Nominal Diameter Stats	8	10	12	15	20	25
Inner Diameter Ød	7	8.9	10.9	11.6	15.7	19.4
Outer Diameter ØD h7	8	10	12	13.6	18.2	22.6
Mass(kg/m)	0.39	0.605	0.875	1.11	2.02	3.1
Ball Center ØBCD	9.3	11.6	13.6	15	20	25
Tolerance μ m	0 -15	0 -18	0 -18	0 -18	0 -21	0 -21



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Hollow Spline Shaft

Table 3.2.2 Hollow Spline Shaft Cross-Sectional Shape Unit: mm

Nominal Diameter Stats	8	10	12
Inner Diameter Ød	3	4	6
Outer Diameter ØD h7	8	10	12
Mass(kg/m)	0.33	0.51	0.66
Ball Center ØBCD	9.3	11.6	13.6
Tolerance μ m	0 -15	0 -18	0 -18

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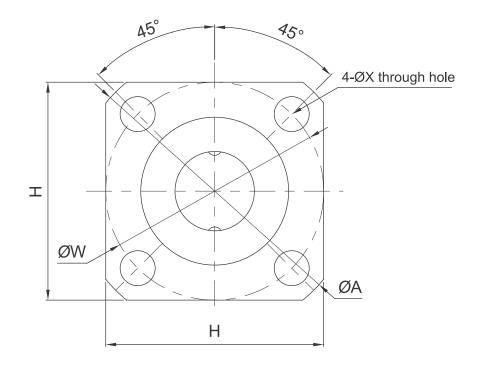








SOF Series Specifications

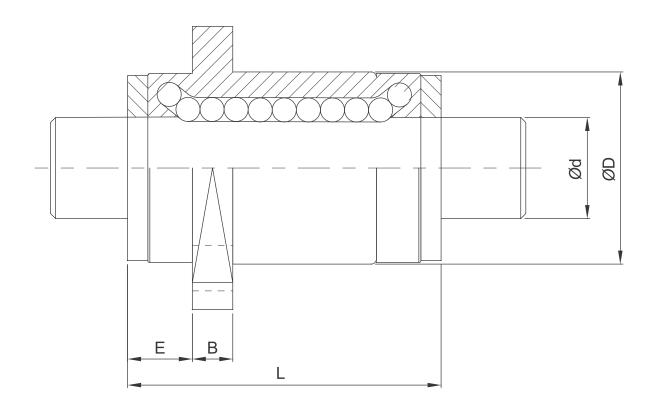


Model No.	Diameter		Spline Nut Dimension									
	d	Row	D	L	А	В	Е	F	W	Mounting Hole		
	h7									X		
SOF008	8	2	15	25	28	3.8	5.2	22	22	3.4		
SOF010	10	2	19	30	36	4.1	5.9	28	28	4.5		
SOF012	12	2	21	35	38	4	6	30	30	4.5		
SOF015	13.6	2	23	40	40	4.5	6.5	31	32	4.5		
SOF020	18.2	2	30	50	46	5.5	8.5	35	38	4.5		
SOF025	22.6	2	37	60	57	6.6	10.4	43	47	5.5		



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	Basic Load Rating		Basic Torsion		Static Permissible Moment		Mass	
Model No.	С	C ₀	Ст	Сот	MA1	MA2	Spline Nut	Spline Shaft
	kgf	kgf	kgf · m	kgf · m	kgf · m	kgf · m	g	kg/m
SOF008	121	136	0.56	0.63	0.34	2.24	23.5	0.39
SOF010	192	219	1.11	1.27	0.71	4.23	45	0.61
SOF012	222	274	1.51	1.87	1.08	6.02	59	0.88
SOF015	426	619	3.19	4.65	2.83	15.49	77	1.11
SOF020	673	922	6.73	9.22	4.95	29.36	150	2.02
SOF025	1142	1458	14.17	18.14	9.46	56.17	255	3.10

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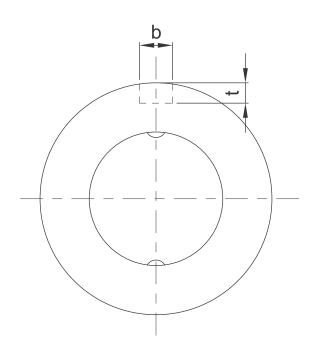
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SOT Series Specifications



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Shaft diameter

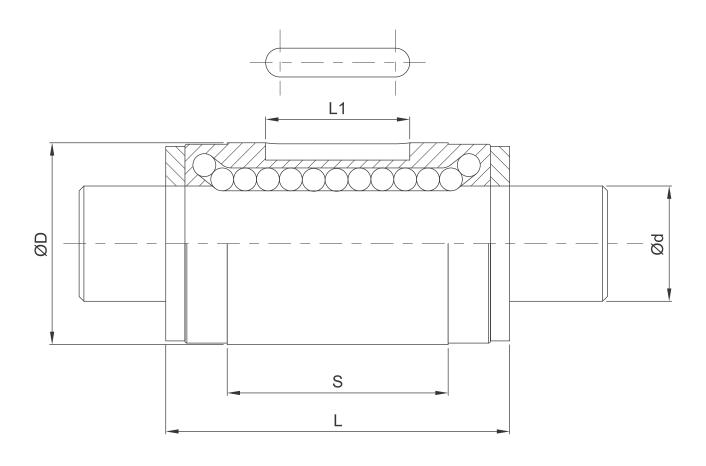
	Diameter		Spli	ne Nut	Keyway Dimensions			
Model No.	d	Row	_			1.4	b	t
	h7		D L S		3	L1	H8	+0.05 ~ 0
SOT008	8	2	15	25	14.6	8.5	2.5	1.5
SOT010	10	2	19	30	18.2	11	3	1.8
SOT012	12	2	21	35	23	15	3	1.8
SOT015	13.6	2	23	40	27	20	3.5	2
SOT020	18.2	2	30	50	33	26	4	2.5
SOT025	22.6	2	37	60	39.2	29	5	3



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🔀 فكس : 33985603 (021)





	Basic Load Rating		Basic Torsion		Static Permissible Moment		Mass	
Model No.	С	C ₀	Ст	Сот	MA1	MA2	Spline Nut	Spline Shaft
	kgf	kgf	kgf · m	kgf · m	kgf · m	kgf · m	g	kg/m
SOT008	121	136	0.56	0.63	0.34	2.24	15.9	0.39
SOT010	192	219	1.11	1.27	0.71	4.23	31.5	0.61
SOT012	222	274	1.51	1.87	1.08	6.02	44	0.88
SOT015	426	619	3.19	4.65	2.83	15.49	59.5	1.11
SOT020	673	922	6.73	9.22	4.95	29.36	130	2.02
SOT025	1142	1458	14.17	18.14	9.46	56.17	220	3.10

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